

A scenario-based feasibility analysis of autonomous robot deliveries

Qureshi AG, Taniguchi E.

Transportation research procedia

2024; 79:76-83

ARTICLE IDENTIFIERS

DOI: 10.1016/j.trpro.2024.03.012

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: not available

pISSN: 2352-1465

eISSN: not available

OCLC ID: 893979151

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.