

## **Quadruped robot control: an approach using body planar motion control, legs impedance control and Bézier curves**

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Sensors (Basel)

2024; 24(12):e3825

### **ARTICLE IDENTIFIERS**

DOI: 10.3390/s24123825

PMID: 38931609

PMCID: not available

### **JOURNAL IDENTIFIERS**

LCCN: 2002242115

pISSN: not available

eISSN: 1424-8220

OCLC ID: 47250782

CONS ID: not available

US National Library of Medicine ID: 101204366

This article was identified from a query of the SafetyLit database.