

Evaluation of force pain thresholds to ensure collision safety in worker-robot collaborative operations

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Frontiers in robotics and AI

2024; 11:e1374999

ARTICLE IDENTIFIERS

DOI: 10.3389/frobt.2024.1374999

PMID: 38651053

PMCID: PMC11033501

JOURNAL IDENTIFIERS

LCCN: 2015263051

pISSN: not available

eISSN: 2296-9144

OCLC ID: 884073051

CONS ID: not available

US National Library of Medicine ID: 101749350

This article was identified from a query of the SafetyLit database.