

An obstacle avoidance approach for UAV path planning

Bashir N, Boudjit S, Dauphin G, Zeadally S.

Simulation modelling practice and theory

2023; 129:e102815

ARTICLE IDENTIFIERS

DOI: 10.1016/j.simpat.2023.102815

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: 2002227263

pISSN: 1569-190X

eISSN: not available

OCLC ID: 51038724

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.