

An ADAS with better driver satisfaction under rear-end near-crash scenarios: a spatio-temporal graph transformer-based prediction framework of evasive behavior and collision risk

Gao J, Yu B, Chen Y, Bao S, Gao K, Zhang L.

Transportation research part C: emerging technologies

2024; 159:e104491

ARTICLE IDENTIFIERS

DOI: 10.1016/j.trc.2024.104491

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: 93640664

pISSN: 0968-090X

eISSN: 1879-2359

OCLC ID: 27960434

CONS ID: sn 93020242

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.