

A multi-vehicle cooperative control scheme in mitigating traffic oscillation with smooth tracking-objective switching for a single-vehicle lane change scenario

Sun K, Gong S, Zhou Y, Chen Z, Zhao X, Wu X.

Transportation research part C: emerging technologies

2024; 159:e104487

ARTICLE IDENTIFIERS

DOI: 10.1016/j.trc.2024.104487

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: 93640664

pISSN: 0968-090X

eISSN: 1879-2359

OCLC ID: 27960434

CONS ID: sn 93020242

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.