

Roadside LiDAR sensor configuration assessment and optimization methods for vehicle detection and tracking in connected and automated vehicle applications

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Transportation research record

2024; 2678(2):184-203

ARTICLE IDENTIFIERS

DOI: 10.1177/03611981231172949

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: 74032372

pISSN: 0361-1981

eISSN: 2169-4052

OCLC ID: 01259379

CONS ID: not available

US National Library of Medicine ID: 101481512

This article was identified from a query of the SafetyLit database.