

# **Leveraging LiDAR-based simulations to quantify the complexity of the static environment for autonomous vehicles in rural settings**

Abohassan M, El-Basyouny K.

Sensors (Basel)

2024; 24(2):e452

## **ARTICLE IDENTIFIERS**

DOI: 10.3390/s24020452

PMID: 38257547

PMCID: not available

## **JOURNAL IDENTIFIERS**

LCCN: 2002242115

pISSN: not available

eISSN: 1424-8220

OCLC ID: 47250782

CONS ID: not available

US National Library of Medicine ID: 101204366

This article was identified from a query of the SafetyLit database.