

Collision-free motion control with learning features for automated vehicles in roundabouts

Németh B, Farkas Z, Antal Z, Fényes D, Gáspár P.
Transportation research procedia
2023; 72:3545-3552

ARTICLE IDENTIFIERS

DOI: 10.1016/j.trpro.2023.11.746
PMID: unavailable
PMCID: not available

JOURNAL IDENTIFIERS

LCCN: not available
pISSN: 2352-1465
eISSN: not available
OCLC ID: 893979151
CONS ID: not available
US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.