

# **Driving authority allocation model for human-machine co-driving system considering fault tolerant control**

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International journal of vehicle performance

2023; 9(4):404-428

## **ARTICLE IDENTIFIERS**

DOI: 10.1504/IJVP.2023.133853

PMID: unavailable

PMCID: not available

## **JOURNAL IDENTIFIERS**

LCCN: not available

pISSN: 1745-3194

eISSN: 1745-3208

OCLC ID: not available

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.