

Obstacle avoidance maneuver by optimal feedback control using deep learning neural networks

Sago T, Arai Y, Ueyama Y, Harada M.

Transactions of Society of Automotive Engineers of Japan

2023; 54(6):1281-1286

ARTICLE IDENTIFIERS

DOI: 10.11351/jsaeronbun.54.1281

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: not available

pISSN: 0287-8321

eISSN: 1883-0811

OCLC ID: 1076728522

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.