

# **Corrigendum: Optimizing trajectories for highway driving with offline reinforcement learning**

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Frontiers in future transportation

2023; 4:e1320940

## **ARTICLE IDENTIFIERS**

DOI: 10.3389/ffutr.2023.1320940

PMID: unavailable

PMCID: not available

## **JOURNAL IDENTIFIERS**

LCCN: not available

pISSN: not available

eISSN: 2673-5210

OCLC ID: not available

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.