

Personalized driving styles in safety-critical scenarios for autonomous vehicles: an approach using driver-in-the-loop simulations

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Vehicles (Basel)

2023; 5(3):1149-1166

ARTICLE IDENTIFIERS

DOI: 10.3390/vehicles5030064

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: not available

pISSN: not available

eISSN: 2624-8921

OCLC ID: not available

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.