

# **Effectiveness of the autonomous braking and evasive steering system OPREVU-AES in simulated vehicle-to-pedestrian collisions**

Losada, Páez FJ, Luque F, Piovano L.

Vehicles (Basel)

2023; 5(4):1553-1569

## **ARTICLE IDENTIFIERS**

DOI: 10.3390/vehicles5040084

PMID: unavailable

PMCID: not available

## **JOURNAL IDENTIFIERS**

LCCN: not available

pISSN: not available

eISSN: 2624-8921

OCLC ID: not available

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.