

Improved active disturbance rejection speed control for autonomous driving of high-speed train based on feedforward compensation

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Science progress

2023; 106(4):e368504231208505

ARTICLE IDENTIFIERS

DOI: 10.1177/00368504231208505

PMID: 37876287

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: not available

pISSN: 0036-8504

eISSN: 2047-7163

OCLC ID: 04295306

CONS ID: not available

US National Library of Medicine ID: 0411361

This article was identified from a query of the SafetyLit database.