

Does non-motorists' safety perception of autonomous vehicles vary across opinion change stemming from crash occurrence? Investigating perceptions using fixed and random parameter ordered logit models

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Heliyon

2023; 9(9):e19913

ARTICLE IDENTIFIERS

DOI: 10.1016/j.heliyon.2023.e19913

PMID: 37809734

PMCID: PMC10559321

JOURNAL IDENTIFIERS

LCCN: not available

pISSN: not available

eISSN: 2405-8440

OCLC ID: 927164142

CONS ID: not available

US National Library of Medicine ID: 101672560

This article was identified from a query of the SafetyLit database.