

Static modeling and experimental verification for safety evaluation of human-robot interaction in exoskeleton robots

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Journal of Institute of Control, Robotics and Systems

2023; 29(9):726-733

ARTICLE IDENTIFIERS

DOI: 10.5302/J.ICROS.2023.23.0088

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: not available

pISSN: 1976-5622

eISSN: 2233-4335

OCLC ID: not available

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.