

Evasive actions to prevent pedestrian collisions in varying space/time contexts in diverse urban and non-urban areas

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Accident analysis and prevention

2023; 192:e107270

ARTICLE IDENTIFIERS

DOI: 10.1016/j.aap.2023.107270

PMID: 37659276

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: 79009842

pISSN: 0001-4575

eISSN: 1879-2057

OCLC ID: 01460775

CONS ID: not available

US National Library of Medicine ID: 1254476

This article was identified from a query of the SafetyLit database.