

Pedestrian localization with stride-wise error estimation and compensation by fusion of UWB and IMU data

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Sensors (Basel)

2023; 23(10):e4744

ARTICLE IDENTIFIERS

DOI: 10.3390/s23104744

PMID: 37430659

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: 2002242115

pISSN: not available

eISSN: 1424-8220

OCLC ID: 47250782

CONS ID: not available

US National Library of Medicine ID: 101204366

This article was identified from a query of the SafetyLit database.