

Road traffic safety assessment in self-driving vehicles based on time-to-collision with motion orientation

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Accident analysis and prevention

2023; 191:e107172

ARTICLE IDENTIFIERS

DOI: 10.1016/j.aap.2023.107172

PMID: 37406543

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: 79009842

pISSN: 0001-4575

eISSN: 1879-2057

OCLC ID: 01460775

CONS ID: not available

US National Library of Medicine ID: 1254476

This article was identified from a query of the SafetyLit database.