

Modeling driver behavior in critical traffic scenarios for the safety assessment of automated driving

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Traffic injury prevention

2023; 24(Suppl 1):S105-S110

ARTICLE IDENTIFIERS

DOI: 10.1080/15389588.2023.2211187

PMID: 37267008

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: 2002212614

pISSN: 1538-9588

eISSN: 1538-957X

OCLC ID: 49192340

CONS ID: not available

US National Library of Medicine ID: 101144385

This article was identified from a query of the SafetyLit database.