

Empirical analysis of autonomous vehicle's LiDAR detection performance degradation for actual road driving in rain and fog

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Sensors (Basel)

2023; 23(6)

ARTICLE IDENTIFIERS

DOI: 10.3390/s23062972

PMID: 36991683

PMCID: PMC10051412

JOURNAL IDENTIFIERS

LCCN: 2002242115

pISSN: not available

eISSN: 1424-8220

OCLC ID: 47250782

CONS ID: not available

US National Library of Medicine ID: 101204366

This article was identified from a query of the SafetyLit database.