

**Navigation risk assessment of autonomous ships based on entropy
TOPSIS--coupling coordination model**

Zhang W, Zhang Y.

Journal of marine science and engineering

2023; 11(2):e422

ARTICLE IDENTIFIERS

DOI: 10.3390/jmse11020422

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: not available

pISSN: not available

eISSN: 2077-1312

OCLC ID: not available

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.