

State estimation and motion prediction of vehicles and vulnerable road users for cooperative autonomous driving: a survey

Ghorai P, Eskandarian A, Kim YK, Mehr G.

IEEE transactions on intelligent transportation systems

2022; 23(10):16983-17002

ARTICLE IDENTIFIERS

DOI: 10.1109/TITS.2022.3160932

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: not available

pISSN: 1524-9050

eISSN: 1558-0016

OCLC ID: not available

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.