

Improved vehicle LiDAR calibration with trajectory-based hand-eye method

Yuwen X, Chen L, Yan F, Zhang H, Tang J, Tian B, Ai Y.

IEEE transactions on intelligent transportation systems

2022; 23(1):215-224

ARTICLE IDENTIFIERS

DOI: 10.1109/TITS.2020.3009674

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: not available

pISSN: 1524-9050

eISSN: 1558-0016

OCLC ID: not available

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.