

# **Dynamic driving risk potential field model under the connected and automated vehicles environment and its application in car-following modeling**

Li L, Gan J, Ji X, Qu X, Ran B.

IEEE transactions on intelligent transportation systems

2022; 23(1):122-141

## **ARTICLE IDENTIFIERS**

DOI: 10.1109/TITS.2020.3008284

PMID: unavailable

PMCID: not available

## **JOURNAL IDENTIFIERS**

LCCN: not available

pISSN: 1524-9050

eISSN: 1558-0016

OCLC ID: not available

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.