

Development of optimal control of tire force based on driving motor for improvement of xEV handling performance(E-handling)

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Transactions of the Korean Society of Automotive Engineers

2022; 30(11):923-929

ARTICLE IDENTIFIERS

DOI: 10.7467/KSAE.2022.30.11.923

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: not available

pISSN: 1225-6382

eISSN: 2234-0149

OCLC ID: not available

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.