

A sliding mode independent velocity control algorithm using adaptive forgetting factor for lane change of autonomous vehicles based on skid steer

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Transactions of the Korean Society of Automotive Engineers

2022; 30(10):769-784

ARTICLE IDENTIFIERS

DOI: 10.7467/KSAE.2022.30.10.769

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: not available

pISSN: 1225-6382

eISSN: 2234-0149

OCLC ID: not available

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.