

Real-time object behavior prediction based on LiDAR suitable for urban autonomous driving

Jeong J, Kee SC.

Transactions of the Korean Society of Automotive Engineers

2022; 30(7):589-598

ARTICLE IDENTIFIERS

DOI: 10.7467/KSAE.2022.30.7.589

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: not available

pISSN: 1225-6382

eISSN: 2234-0149

OCLC ID: not available

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.