## Proposal of the longitudinal driver model in coordination with vehicle lateral motion based upon jerk information

Yamakado M, Abe M. Transactions of Society of Automotive Engineers of Japan 2008; 39(3):3\_53-3\_58

## **ARTICLE IDENTIFIERS**

DOI: 10.11351/jsaeronbun.39.3\_53

PMID: unavailable PMCID: not available

## **JOURNAL IDENTIFIERS**

LCCN: not available pISSN: 0287-8321 eISSN: 1883-0811 OCLC ID: 1076728522 CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.