

Road-vehicle cooperative speed control for automatic driving vehicle in service area of highway using information on movement prediction of pedestrians

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Transactions of Society of Automotive Engineers of Japan

2015; 46(2):551-557

ARTICLE IDENTIFIERS

DOI: 10.11351/jsaeronbun.46.551

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: not available

pISSN: 0287-8321

eISSN: 1883-0811

OCLC ID: 1076728522

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.