

# **Real-time path planning using clothoid curve for a vehicle turning control to pass through any target point**

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Transactions of Society of Automotive Engineers of Japan

2020; 51(6):1012-1018

## **ARTICLE IDENTIFIERS**

DOI: 10.11351/jsaeronbun.51.1012

PMID: unavailable

PMCID: not available

## **JOURNAL IDENTIFIERS**

LCCN: not available

pISSN: 0287-8321

eISSN: 1883-0811

OCLC ID: 1076728522

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.