Trade-off between safety, mobility and stability in automated vehicle following control: an analytical method

Li X.

Transportation research part B: methodological

2022; 166:1-18

ARTICLE IDENTIFIERS

DOI: 10.1016/j.trb.2022.09.003

PMID: unavailable PMCID: not available

JOURNAL IDENTIFIERS

LCCN: 79645158 pISSN: 0191-2615 eISSN: 1879-2367 OCLC ID: 4827986 CONS ID: sn 79002419

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.