

# **Autonomous driving control in mixed traffic scene by using nonlinear model predictive control and graph theory**

Sumioka T, Nishimiya K, Akuta Y.

Transactions of Society of Automotive Engineers of Japan

2017; 48(6):1353-1358

## **ARTICLE IDENTIFIERS**

DOI: 10.11351/jsaeronbun.48.1353

PMID: unavailable

PMCID: not available

## **JOURNAL IDENTIFIERS**

LCCN: not available

pISSN: 0287-8321

eISSN: 1883-0811

OCLC ID: 1076728522

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.