

Multi-task vehicle platoon control: a deep deterministic policy gradient approach

Berahman M, Rostami-Shahrababaki M, Bogenberger K.
Future transportation
2022; 2(4):1028-1046

ARTICLE IDENTIFIERS

DOI: 10.3390/futuretransp2040057

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: not available

pISSN: not available

eISSN: 2673-7590

OCLC ID: 1284923921

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.