

# **Cooperative path and trajectory planning for autonomous vehicles on roads without lanes: a laboratory experimental demonstration**

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Transportation research part C: emerging technologies

2022; 144:e103813

## **ARTICLE IDENTIFIERS**

DOI: 10.1016/j.trc.2022.103813

PMID: unavailable

PMCID: not available

## **JOURNAL IDENTIFIERS**

LCCN: 93640664

pISSN: 0968-090X

eISSN: 1879-2359

OCLC ID: 27960434

CONS ID: sn 93020242

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.