

# **A global path planning method for unmanned vehicle formation based on pilot-following method**

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Advances in transportation studies

2022; (SI 4):71-80

## **ARTICLE IDENTIFIERS**

DOI: unavailable

PMID: unavailable

PMCID: not available

## **JOURNAL IDENTIFIERS**

LCCN: not available

pISSN: 1824-5463

eISSN: not available

OCLC ID: not available

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.