

Erratum to: Path planning for vehicle active collision avoidance based on virtual flow field

Liu J, Ji J, Ren Y, Huang Y, Wang H.

International journal of automotive technology

2022; 23(1):293

ARTICLE IDENTIFIERS

DOI: 10.1007/s12239-022-0026-x

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: not available

pISSN: 1229-9138

eISSN: 1976-3832

OCLC ID: not available

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.