

**Automated vehicle research by recognizing maneuvering modes using LSTM model ;; LSTM ?? ?? ?? ?? ??? ?? ?? ??? ?? ??**

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Journal of the Korea Institute of Intelligent Transportation Systems

2017; 16(4):153-163

**ARTICLE IDENTIFIERS**

DOI: 10.12815/kits.2017.16.4.153

PMID: unavailable

PMCID: not available

**JOURNAL IDENTIFIERS**

LCCN: not available

pISSN: 1738-0774

eISSN: 2384-1729

OCLC ID: not available

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.