

# **Coordinated control for path-following of an autonomous four in-wheel motor drive electric vehicle**

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Proceedings of the Institution of Mechanical Engineers, Part C: Journal of mechanical engineering science

2022; 236(11):6335-6346

## **ARTICLE IDENTIFIERS**

DOI: 10.1177/09544062211064797

PMID: 35719241

PMCID: PMC9198396

## **JOURNAL IDENTIFIERS**

LCCN: 84650606

pISSN: 0954-4062

eISSN: 2041-2983

OCLC ID: 9408679

CONS ID: sn 89038350

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.