

Automatic identification of vehicle partial occlusion in data collected by roadside LiDAR sensors

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Transportation research record

2022; 2676(5):708-718

ARTICLE IDENTIFIERS

DOI: 10.1177/03611981211069347

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: 74032372

pISSN: 0361-1981

eISSN: 2169-4052

OCLC ID: 01259379

CONS ID: not available

US National Library of Medicine ID: 101481512

This article was identified from a query of the SafetyLit database.