

A longitudinal car-following risk assessment model based on risk field theory for autonomous vehicles

Wu B, Yan Y, Ni D, Li L.

International journal of transportation science and technology

2021; 10(1):60-68

ARTICLE IDENTIFIERS

DOI: 10.1016/j.ijtst.2020.05.005

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: not available

pISSN: 2046-0430

eISSN: not available

OCLC ID: not available

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.