

Autonomous navigation at unsignalized intersections: a coupled reinforcement learning and model predictive control approach

Bautista-Montesano R, Galluzzi R, Ruan K, Fu Y, Di X.
Transportation research part C: emerging technologies
2022; 139:e103662

ARTICLE IDENTIFIERS

DOI: 10.1016/j.trc.2022.103662
PMID: unavailable
PMCID: not available

JOURNAL IDENTIFIERS

LCCN: 93640664
pISSN: 0968-090X
eISSN: 1879-2359
OCLC ID: 27960434
CONS ID: sn 93020242
US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.