

LiDAR- and radar-based robust vehicle localization with confidence estimation of matching results

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Sensors (Basel)

2022; 22(9):3545

ARTICLE IDENTIFIERS

DOI: 10.3390/s22093545

PMID: 35591236

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: 2002242115

pISSN: not available

eISSN: 1424-8220

OCLC ID: 47250782

CONS ID: not available

US National Library of Medicine ID: 101204366

This article was identified from a query of the SafetyLit database.