

# **Identification of a step-and-brake controller of a human based on prediction of capturability**

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Frontiers in robotics and AI

2022; 9:e729593

## **ARTICLE IDENTIFIERS**

DOI: 10.3389/frobt.2022.729593

PMID: 35572372

PMCID: PMC9096700

## **JOURNAL IDENTIFIERS**

LCCN: 2015263051

pISSN: not available

eISSN: 2296-9144

OCLC ID: 884073051

CONS ID: not available

US National Library of Medicine ID: 101749350

This article was identified from a query of the SafetyLit database.