

Design of beaver-like hind limb and analysis of two swimming gaits for underwater narrow space exploration

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Journal of intelligent and robotic systems

2022; 104(4):e65

ARTICLE IDENTIFIERS

DOI: 10.1007/s10846-022-01610-7

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: 88659214

pISSN: 0921-0296

eISSN: 1573-0409

OCLC ID: 18197178

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.