

Dynamic lane changing trajectory planning for CAV: a multi-agent model with path preplanning

Zong F, He Z, Zeng M, Liu Y.

Transportmetrica B: transport dynamics

2022; 10(1):266-292

ARTICLE IDENTIFIERS

DOI: 10.1080/21680566.2021.1989079

PMID: unavailable

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: not available

pISSN: 2168-0566

eISSN: not available

OCLC ID: not available

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.