

An autonomous driving approach based on trajectory learning using deep neural networks

Wang D, Wang C, Wang Y, Wang H, Pei F.
International journal of automotive technology
2021; 22(6):1517-1528

ARTICLE IDENTIFIERS

DOI: 10.1007/s12239-021-0131-2
PMID: unavailable
PMCID: not available

JOURNAL IDENTIFIERS

LCCN: not available
pISSN: 1229-9138
eISSN: 1976-3832
OCLC ID: not available
CONS ID: not available
US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.