

Leg-ligament-thigh-trunk dynamic model to describe posture recovery after double-leg landing task

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Annual International Conference of the IEEE Engineering in Medicine and Biology Society.
2021; 2021:4816-4819

ARTICLE IDENTIFIERS

DOI: 10.1109/EMBC46164.2021.9629955

PMID: 34892287

PMCID: not available

JOURNAL IDENTIFIERS

LCCN: not available

pISSN: 2375-7477

eISSN: 2694-0604

OCLC ID: not available

CONS ID: not available

US National Library of Medicine ID: 101763872

This article was identified from a query of the SafetyLit database.