

# **Stable trajectory planning and energy-efficiency control allocation of lane change maneuver for autonomous electric vehicle**

Xu L, Yin G, Li G, Hanif A, Bian C.

Journal of intelligent and connected vehicles

2018; 1(2):55-65

## **ARTICLE IDENTIFIERS**

DOI: 10.1108/JICV-12-2017-0002

PMID: unavailable

PMCID: not available

## **JOURNAL IDENTIFIERS**

LCCN: 2020204353

pISSN: 2399-9802

eISSN: not available

OCLC ID: 1018199239

CONS ID: not available

US National Library of Medicine ID: not available

This article was identified from a query of the SafetyLit database.